Sizing Form

| Customer Name / | | Filling Date (DD/MM/YEAR) / |
|--|-----|-----------------------------|
| Contact Person / | | Telephone / |
| E-mail / | | Fax / |
| 5. Point-to-Point Motion with constant velocity section Property: Work performed under constant velocity Application: Scanning, inspection, cutting etc. | | |
| a. Motion Condition | | Velocity |
| (1) Load Mass | kg | 1 |
| (2) Effective Stroke | m | |
| (3) Max. Velocity | m/s | Max. Velocity |
| (4) Acceleration Time | S | |
| (5) Dwell Time | S | Stroke → Dwell Time → |
| b. Driver Condition | | Time |
| (1) Max. Output Voltage | V | Acceleration Deceleration |
| (2) Continuous Current | A | Cycle Period / 2 |
| (3) Peak Current | Α | |
| | | |
| c. Encoder | | f. Motion Direction |
| (1) Analog Digital | | (1) Horizontal |
| (2) Resolution | μm | (2) Vertical |
| d. Working Environment | | (3) Tilt Degrees |
| (1) Room Temperature | | g. Installation Method |
| (2) Constant Temperature C | | (1) Lying Flat |
| (3) Vacuum Torr | | (2) Urtically standing |
| (4) Clean Room Level | | (3) Wall Mount |
| | | |
| e. Motion Precision | | h. Space Restrictions |
| (1) Positioning Accuracy | μm | (1) None |
| (2) Repetitive Accuracy | μm | (2) |